

# MLS Pressure Boundaries for Divergence-Free and Viscous SPH Fluids - Appendix

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## 1 Mass of a boundary particle

Iterative solvers such as PCISPH [11], IISPH [5] or DFSPH [4] compute a pressure field  $p$  and apply pressure accelerations of the form

$$\mathbf{a}_f^p = - \sum_j m_j \left( \frac{p_f}{\rho_f^2} + \frac{p_j}{\rho_j^2} \right) \nabla W_{fj} - \sum_b m_b \left( \frac{p_f}{\rho_f^2} + \frac{p_b}{\rho_b^2} \right) \nabla W_{fb} \quad (1)$$

to fluid particles  $f$  [3]. Here,  $j$  and  $b$  denote fluid and boundary neighbors of fluid particle  $f$ , respectively. Equation (1) requires a notion of mass  $m_b$  and density  $\rho_b$  at boundary particles  $b$ .

The mass  $m_b$  at a boundary particle  $b$  can be geometrically motivated from the boundary particle volume  $V_b$  [1, 10, 2], i.e. the mass  $m_b$  can be derived from the relation  $m_b = \rho_b V_b$ . Since the density  $\rho_b$  is typically set to the rest density of the adjacent fluid particle [1], i.e.

$$\rho_b = \rho_f, \quad (2)$$

the mass  $m_b$  of a boundary particle  $b$  can be computed as

$$m_b = \rho_f^0 V_b^0, \quad (3)$$

where  $\rho_f^0$  denotes the rest density of fluid particle  $f$  and the rest volume  $V_b^0$  is [2]

$$V_b^0 = \frac{\gamma}{\sum_{b_b} W_{bb_b}}. \quad (4)$$

The computation of Eq. (4) only processes boundary neighbors  $b_b$  of a boundary particle  $b$  as the rest volume does not depend on possibly adjacent fluid particles [2]. As only one layer of boundary particles is used to represent the surface of the boundary [1], the coefficient  $\gamma$  accounts for an incomplete neighborhood. The coefficient depends on the choice of the SPH kernel function. For the cubic spline kernel [7] with a smoothing length of two times the particle size  $h$ ,  $\gamma \approx 0.7$  [2]. This motivated by the fact that  $0.7 / \sum_{b_b} W_{bb_b} = h^3$  for boundary particles that are evenly sampled in a plane. See Fig. 1 for an illustration of the derivation.



co-planar. In these cases, we follow [8] and use safe inversion via Singular Value Decomposition (SVD) [9] to avoid the problems with singular matrices. We use the SVD implementation of [6].

Also, we set  $\beta_b$ ,  $\gamma_b$  and  $\delta_b$  to zero if  $\|\sum_{b_f} (\bar{x}_{b_f}, \bar{y}_{b_f}, \bar{z}_{b_f})^T p_{b_f} V_{b_f} W_{bb_f}\| < \epsilon$ , where  $\epsilon$  is a small value, e.g.,  $10^{-5}$ . This results in a pressure value  $p_b = \alpha_b$ .

## References

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